

# Introduzione alle tecniche di ottimizzazione ed esperienze nel laboratorio MilleChili

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# Outline

- 1 Introduction
- 2 Optimization
- 3 Structural optimization
- 4 Application examples
- 5 Automotive hood
- 6 Rear bench
- 7 Automotive chassis
- 8 Conclusions



# MilleChili Lab and aim of the research

## MilleChili Lab

MilleChili Lab was born in february 2009 from a collaboration between *Ferrari SpA* and the *Università degli Studi di Modena e Reggio Emilia*



## Objectives of the laboratory

- Design a novel automotive chassis in view of **weight reduction** and in fulfilment of given structural performance constraints according to Ferrari standards
- Offer a consulting service supporting Ferrari designers in the field of structural optimization of automotive components



# MilleChili Lab rationale and main tools

## A different approach to design

company know-how and  
designer experience



systematic design by means  
of **optimization** techniques

## Structural optimization techniques

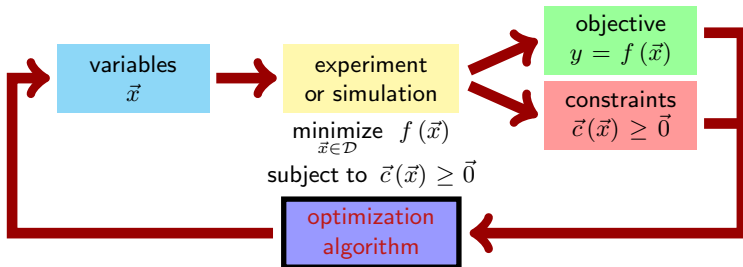
- Topology
- Topometry
- Topography
- Size
- Shape



# Optimization

## A definition

In an optimization problem we seek values of the **variables** that lead to an optimal value of the **function** that is to be optimized



# Techniques for approaching an optimization problem

## Techniques

- Design of Experiments (DOE)
- Response Surface Modelling (RSM)
- Deterministic Optimization
- Stochastic Optimization
- Robust Design Analysis (RDA)



# Design of Experiments I

## DOE

Is the art of collecting as much information as possible about the problem at hand using the least amount of resources

- Technique borrowed from statistics
- In optimization is used for sampling the design space
- The aims of the sampling may be:
  - understand to what extent the variables affect the optimization problem
  - to better reshape the design space for further optimization
  - provide the information for creating a RSM

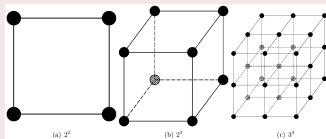


# Design of Experiments II

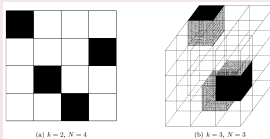
## DOE Methods

A large set of DOE methods are available, each having different characteristics and being most suitable for specific different purposes, to cite a few:

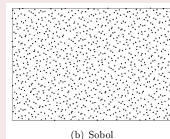
### • Full Factorial



### • Latin Hypercube



### • Sobol





# Response Surface Modelling I

## RSM

Aims at interpolating or approximating the data collected through DOE in order to create an analytic or parametric response surface (or meta-model) to be used in optimization

$$f(\mathbf{x}) = \hat{f}(\mathbf{x}) + \varepsilon(\mathbf{x})$$

- Relying on a meta-model is always a risk
- The goodness of the meta-model strictly depends on the quality of the DOE data, and the nature of the function to be approximated
- When collecting data is expensive it is necessary to adopt a DOE+RSM approach in optimization



# Response Surface Modelling II

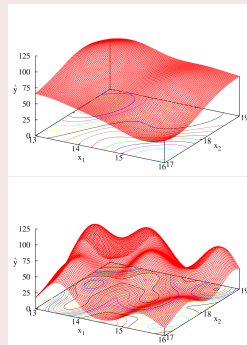
## RSM Methods

Several RSM methods exist, each having different characteristics and being most suitable for specific different purposes, to cite a few:

- Least-Squares
- Kriging
- Radial Basis Functions

Most methods are weight-based

$$\hat{f}(\mathbf{x}) = \sum_{i=1}^N \lambda_i(\mathbf{x}) f(\mathbf{x}_i), \quad \sum_{i=1}^N \lambda_i = 1$$



# Deterministic Optimization I

## Deterministic Optimization, AKA Mathematical Programming

Is the classical branch of optimization algorithms in mathematics

- It embodies algorithms that rely on rigorous algebraic methods
- Most algorithms are gradient-based
- The methods converge very fast, and are even faster if the gradients do not need to be approximated with finite-difference methods
- They are local methods
- They are inherently single-objective
- Constraints handling must be carefully addressed, and mis-convergence may easily occur



# Deterministic Optimization II

## Deterministic Optimization Methods

Several deterministic optimization algorithms exist, and they may be classified into a few main categories:

- Newton and Quasi-Newton Methods
- Conjugate Direction Methods
- Non Gradient-Based Methods

Of course each algorithm has its own characteristics that makes it most suitable to address certain types of problems. Nevertheless a few algorithms have imposed themselves for their fast convergence and stability, in particular:

- BFGS (for unconstrained optimization)
- NLPQLP (for constrained optimization)
- Nelder & Mead Simplex (slower but simple and stable)

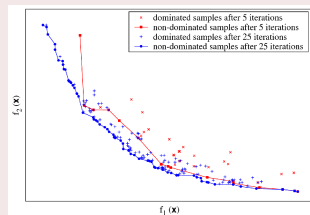


# Stochastic Optimization I

## Stochastic Optimization

Is the family of optimization methods that are non-rigorous mathematically, and include some stochastic element in their algorithmic formulation:

- Usually the algorithms aim at mimicking aspects of nature in fancy ways
- Randomness allows the samples to move freely in the design space
- This gives the algorithms the chance to better explore the design space, making the optimization global
- The price to pay is in terms of a much slower convergence
- Stochastic algorithms are inherently multi-objective
- The result of a multi-objective optimization is given by the set of non-dominated samples (Pareto front)



# Stochastic Optimization II

## Stochastic Optimization Methods

Among the stochastic optimization methods, a wide popularity has been achieved by:

- Genetic Algorithms
- Evolutionary Algorithms

Among the remaining methods, the following are noteworthy:

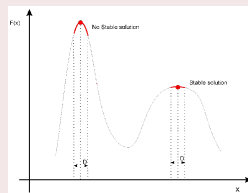
- Game Theory Optimization
- Particle Swarm Optimization



# Robust Design Analysis I

## Optimum vs Robust

- Finding the optimum configuration is often not enough
- It is important to test the robustness of the solution found
- A solution is said robust if it is little affected by uncertainties
- Robustness is evaluated by including the effect of the variables uncertainties through a Montecarlo sampling in the neighbourhood of a configuration
- The main issue in the robustness analysis is the difficulty in evaluating the uncertainties of the variables



# Robust Design Analysis II

## RDA Methods

Two different kind of approaches to RDA exist:

- Multi-Objective Robust Design Optimization (MORDO)

$$\begin{array}{ll} \underset{\mathbf{x}}{\text{minimize}} & f(\mathbf{x}) \\ \text{subject to} & \mathbf{c}(\mathbf{x}) \leq \mathbf{0} \end{array} \quad \Rightarrow \quad \begin{array}{ll} \underset{\mathbf{x}}{\text{minimize}} & \mu(\mathbf{x}) \\ \underset{\mathbf{x}}{\text{minimize}} & \sigma^2(\mathbf{x}) \\ \text{subject to} & \mathbf{c}(\mathbf{x}) \leq \mathbf{0} \end{array}$$

- Reliability Analysis (RA)

aims at the evaluation of the probability that the configuration will satisfy a given minimum performance requirement





# The Optimization Process

## General Guidelines

- Every class of techniques seen so far and every possible optimization algorithm cannot be thought of as being self-sufficient, and being the solution to any kind of problem
- Every class of techniques/algorithms have their own peculiarities that makes them suitable or unsuitable to properly solve a given problem
- The knowledge of the optimization methods and of the problem at hand must concur in guiding the designer in addressing optimization properly
- All the classes of techniques should be involved in solving an optimization process
- No one-shot approach to optimization should be possibly adopted



# Structural Optimization: Shape vs Topology

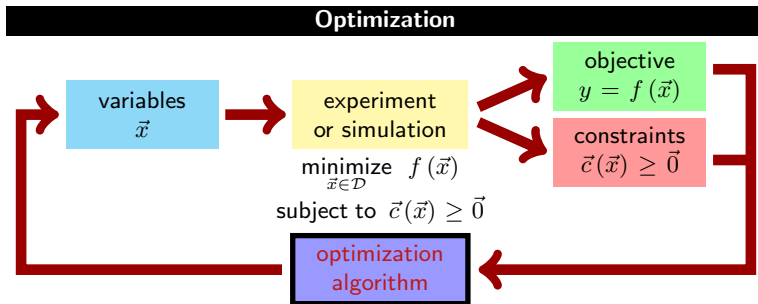
## Shape vs Topology

- When optimizing the shape of an object, we usually resort to a parameterization of the shape, and solve the problem using the techniques proposed before
- Nevertheless, in this way it is not possible to define the optimum topology of the object
- To achieve this a different turn of mind over the optimization problem is needed, and this is the goal of topology optimization

*The art of structure is where to put the holes*



# What is structural optimization?



Structural optimization	
variables (design space)	→ FE domain (1 variable per element)
experiment or simulation	→ finite elements analysis
objective	→ mass minimization
constraints	→ stiffness, displacements, modal, ...
optimization algorithm	→ gradient based (CONLIN or MMA)



# Variables in structural optimization

optimization method	variable	applicability
topology	element density (material distribution)	solid & shell elements
topometry	element thickness (thickness distribution)	shell elements
topography	element offset (bead patterns)	shell elements
size	component thickness (thickness distribution)	shell elements
shape	morphing weight factors (deformations superposition)	solid & shell elements



# A quick introduction to topology optimization

## Basic equations: SIMP method for topology optimization

$$x_i \in (0, 1] \quad \forall i$$

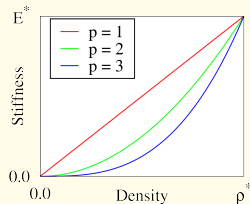
$$\rho_i(x_i) = x_i \rho^*$$

$$E_i(x_i) = x_i^p E^*$$

 $\Rightarrow$ 

$$\frac{\rho_i(x_i)}{E_i(x_i)} = x_i^{1-p} \frac{\rho^*}{E^*}$$

$$\frac{\partial E_i(x_i)}{\partial x_i} = p x_i^{p-1} E^*$$

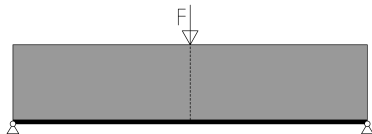


## Main control parameters in topology optimization

- penalty factor  $p$
- sensitivity filter  $r$



# An example: topology optimization of a bridge



$p \rightarrow$ $r \downarrow$	1.0	1.5	2.0	2.5
1.0				
1.2				
1.5				

images obtained with the code by Sigmund, available from <http://www.topopt.dtu.dk/files/top.m>

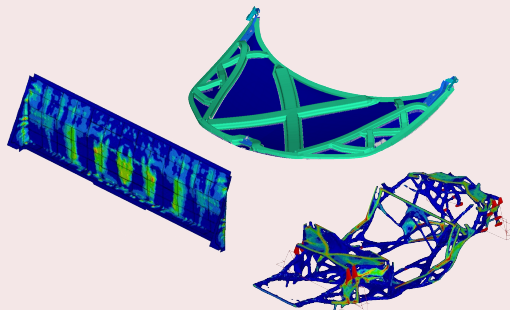


## Application examples

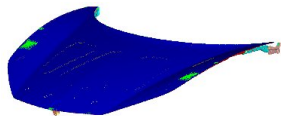
In the following slides a few application examples of structural optimizations related to the automotive chassis weight reduction will be given, in detail:

### Examples and optimizations performed

- Automotive hood
  - topology
    - ↳ topometry
    - ↳ size
- Rear bench
  - topography + size
- Automotive chassis
  - topology
    - ↳ topometry
    - ↳ size



## Numerical model, constraints and target



- the reference model is Ferrari F458 Italia
- the objective of the optimization is the hood weight reduction
- the goal has to be reached by modifying the inner panel and its reinforcements with no performance loss compared to the reference model
- the inner panel is connected to the external skin with structural glue
- the outer shape, the hinges and the latch are non modifiable



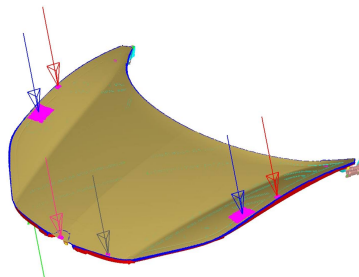


# Loadsteps

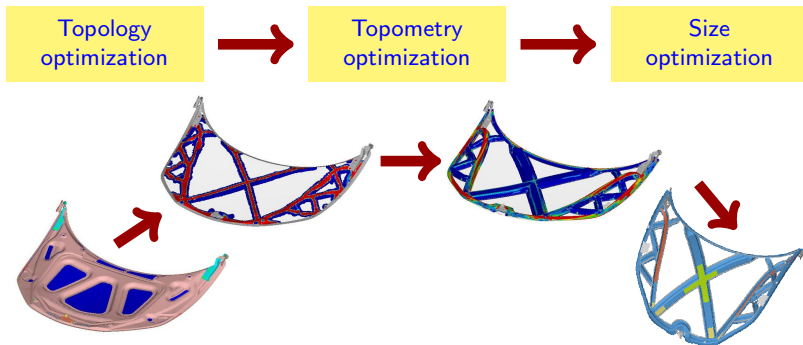
Six different loadsteps have been considered in the FE analyses, one for each hood stiffness target

- bending global stiffness
- torsional global stiffness
- flaps bending stiffness
- hinges attachment stiffness
- latch attachment stiffness
- stabilus attachment stiffness

FE tests replicate experimental setups



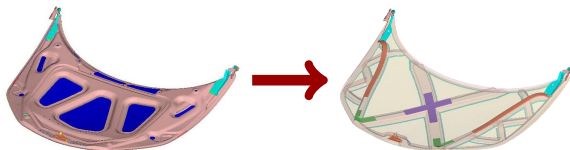
# Optimization process



- the mass distribution proposed by topology optimization is very different from the reference substructure
- topometry optimization locate critical areas needing reinforcements
- size optimization is used for sizing reinforcements granting structural stiffness and weight reduction



# Results

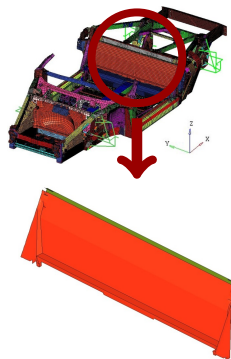


global torsional stiffness	− 0.2%
global bending stiffness	+ 2.4%
flaps bending stiffness	+ 1.2%
hinges attachment stiffness	+ 1.2%
latch attachment stiffness	+ 5.5%
stabilus attachment stiffness	+10.9%
hood weight	−12.4%

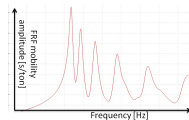
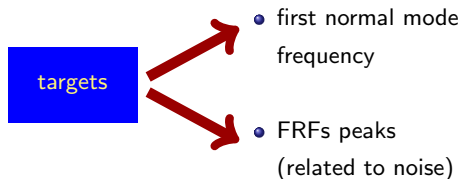


# Numerical model

- the rear bench is made of a thin plate of aluminum
- its vibration characteristics are fundamental for passengers comfort
- for this reason the plate is covered with patches of damping material
- the FE property used in this application allows a double material layer to be defined in order to account for the bonding between aluminum and damping material



# Targets and optimization process



the process adopted includes concurrent plate beads pattern and damping material distribution optimizations

Size  
optimization



Topography  
optimization

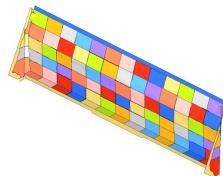
damping material thickness  $0 \div 3.2$  mm

beads distribution on the plate

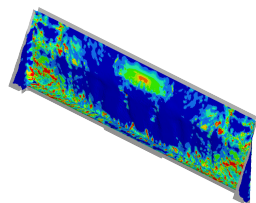
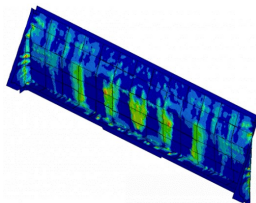
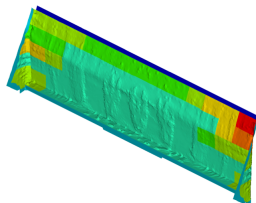


## Variables and results

For size optimization a single variable/component is adopted for the aluminum plate thickness, while several variables/components are considered for the damping material



In comparison to the reference model several optimization runs brought to weight reductions in the range 6 to 10%



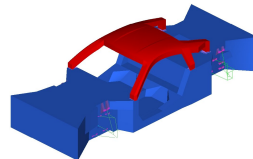
# Topology domains

Reference model

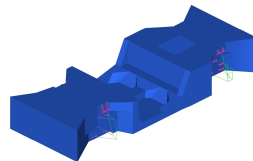


- wheelbase and track
- suspensions, seats, engine, and gearbox joints position
- suspensions layout
- passenger compartment, engine, and gearbox size and location
- chassis material (aluminum)

Coupé topology domain



Spider topology domain



# Optimization constraints

- ① **global** bending and torsional **stiffness** of the structure
  - sills displacement
  - wheel centre displacement
- ② head-on **crash** linearization
  - seat, engine, A-pillar, pedal, flame shield, dashboard displacements
  - compliance
- ③ **modal response** of the structure
  - first natural mode
- ④ **local stiffness** of the suspensions, engine, and gearbox joints
  - wheel centres displacements
  - engine and gearbox displacements





# Optimization process

- the chassis is required to be symmetric in the spanwise direction
- increasing complexity optimizations adding the constraints one at a time



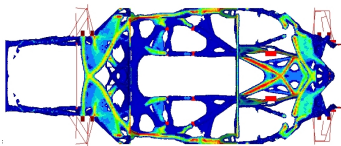
# Results

Coupé chassis

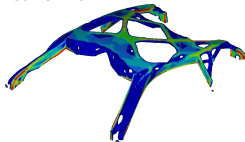
*left view*



*top view*



*roof isometric view*

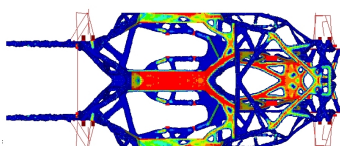


Spider chassis

*left view*



*top view*



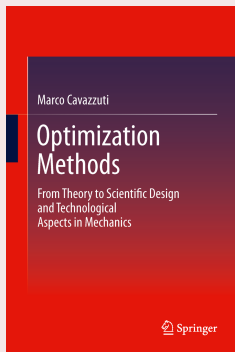
# Conclusions

- Structural optimization methods were introduced and application examples discussed showing their potential
- Optimization allows addressing the design process in a more **automatic** and **unitary** way
- Structural optimization could provide large benefits to industries by boosting their structural design capabilities
- Its application requires some knowledge and care, particularly in the choice of the domain and the optimization constraints
- Different optimization methods have different features: a **combined approach** adopting different techniques is recommended for a better exploitation of these features



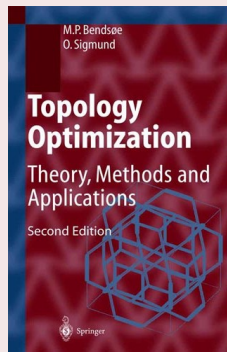
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## On Topology Optimization



M.P. Bendsøe, O. Sigmund, *Topology optimization*, Springer, 2nd ed., 2013



# Thank you for your attention!

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